# SEMESTER V

Sl. No.	Code	Title	L	Т	Р	C	Category
1	EE3001	Microprocessors & Microcontrollers	3	-	-	3	PT
2	EE3002	Control Systems -1	3	-	-	3	РТ
3	EE3003	Electrical Machines - II	3	-	-	3	PT
4	EE3004	Power Systems - I	3	-	-	3	РТ
5		Elective - 1	3	-	-	3	РТ
6		Elective - 2	3	-	-	3	PT
7	ME3094	Mechanical Engineering Lab	-	-	3	2	РТ
8	EE3091	Electrical Machines Lab - I	-	-	3	2	PT
			18	-	6	22	

# LIST OF ELECTIVES - V<sup>TH</sup> SEMESTER

S.No	Code	Title	Credit
1	EE3021	Electrical Engineering Materials	3
2	EE3022	Network Analysis & Synthesis	3
3	EE3023	Optimization Techniques and Algorithms	3
4	EE3024	Special Machines and Linear Machines	3
5	EE3025	Electric Power Utilization	3
6	EE3026	Dynamic Analysis of Electrical Machines	3
7	EE3027	Linear System Theory	3
8	EE3028	High Voltage Engineering	3
9	EE3029	Non-conventional Energy Systems and Application	3
10	EE3030	Applications of Analog Integrated Circuits	3

**BRIEF SYLLABI** 

#### EE 3001 MICROPROCESSORS AND MICROCONTROLLERS

**Pre-Requisites : None** 

Introduction – Number systems, Memory, system organization – PIC as a tool to learn micro controllers – Peripherals in the microcontroller - Programming and simulation - Intel 8086 microprocessor - Its architecture and programming – Interfacing chips – Timer – Peripheral interface – DMA controller – Serial communication controller.

#### **Total Hours : 42 Hours**

#### EE3002 CONTROL SYSTEMS -1

**Pre-requisites : None** 

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3	0	0	3

General scheme of control systems - - ON-OFF, P, PI ,Pd and PID control - Modelling of dynamic systems-Transfer function - State space modeling- concept of state - state equations general formulation - matrix-vector formulation for linear systems- state model for typical systems- state space model from differential equations and transfer function - canonical models - non-uniqueness of state models -transfer function from state model. Time domain analysis of SISO control systems- Solution of linear time invariant state equation .Stability of linear systems -- Frequency domain methods -- Frequency domain specifications -- correlation with time domain parameters.Discrete time systems-Sampling Process- Z Transform and Inverse Z Transform- Pulse transfer functions - State model for discrete time systems- time response from z transform and state models.

**Total Hours: 42 Hours** 

#### **EE3003 ELECTRICAL MACHINES II**

**Prerequisite:** None

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Alternators - construction - principle of operation - armature reaction - phasor diagrams - predetermination of voltage regulation - two reaction theory - methods of excitation - synchronous machines - power angle characteristics - reactance power - load sharing upon parallel operation - automatic synchronizing - effect of change in fuel supply and excitation - synchronizing power and torque - automatic voltage regulators synchronous motor - principle of operation - equivalent circuit - phasor diagram - mechanical load diagram - V curves - inverted V curves - O curves - torque and power relations - hunting - different starting methods - three phase induction motors - construction - principle of operation - phasor diagram - equivalent circuit - torque slip characteristics - no-load and blocked rotor tests - circle diagram - double cage rotors - cogging and crawling induction generators - single phase induction motors - double revolving field theory - equivalent circuit - starting methods and speed control of three phase induction motors - starting methods of single phase induction motors. **Total Hours: 42 Hours** 

#### EE3004 POWER SYSTEMS – I

**Pre-requisites : None** 

Conventional sources of electrical energy- Overhead transmission systems-Transmission line parameters-Distribution systems- Energy Conservation Measures- Power quality issues and mitigation techniquesdistribution system planning and automation-Switch gear and protection.

**Total Hours: 42 Hours** 

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### **EE3021 ELECTRICAL ENGINEERING MATERIALS**

**Pre-requisites:** None

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3	0	0	3

Conducting materials: quantum free electron theory- Fermi-Dirac distribution - Materials for electric resistancesgeneral electric properties: brushes of electrical machines, lamp filaments ,fuses and solder. -Semiconductors: Mechanism of conduction in semiconductors. Magnetic materials: magnetic materials used in electrical machines instruments and relays -Dielectrics - Insulating materials - Special purpose materials and processes -Super conductors –Materials for electronic components –

#### **Total Hours: 42 Hours**

#### **EE3022 NETWORK ANALYSIS & SYNTHESIS**

#### Pre-requisite: EE2005 Circuits & Networks

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Network Topology: Loop analysis of networks (with independent and dependant sources) –Mesh analysis-Duality –Node pair analysis – Analysis using generalized branch model (node, loop and node pair analysis) – Tellegen's theorem for lumped parameter network in topological form -

Network functions for one port and two port networks – Hurwitz polynomials – properties - Brune's positive real functions – Properties of positive real functions - Necessary and sufficient conditions for positive real functions – Sturm's test for positive real functions-Synthesis of reactive one-ports by Foster's and Cauer's methods - Synthesis of LC, RC and RL driving-point functions – RLC one terminal-pair network synthesis – Minimum positive real functions – Brune's method of RLC synthesis – Series Parallel realization – Chop- chop method - The method of Bott and Duffin –Two terminal-pair synthesis –The LC ladder development –The RC ladder development – Gullimen's transfer admittance synthesis

**Total Hours : 42 Hours** 

#### **EE3023 OPTIMIZATION TECHNIQUES AND ALGORITHMS**

**Pre-Requisites : None** 

Concepts of optimization- Classical Optimization Techniques- Linear programming- Engineering Applications
Nonlinear programming- Unconstrained optimization- Basic decent methods- Nonlinear programming-Dynamic
programming- Optimization programming, tools and Software: MATLAB- SIMULINK, FSQP, SOLVER LINDO etc.

**Total Hours: 42 Hours** 

### **EE3024 SPECIAL MACHINES AND LINEAR MACHINES**

#### Prerequisite: EE2007 Electrical Machines I

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Servo motors -Requirement of a good servomotor, Types of servomotors, construction, operating principle and application. Symmetrical components applied to two - phase servo motors - servo motor torque. Stepper motors - construction features - method of operation half stepping and the required switching sequence - the reluctance type stepper motor. Reluctance motors - construction, principle and classification Hysteresis motors- construction, principle and classification, torque develop and slip. Universal motors - characteristics - circuit model and phasor diagram. Linear machines - basic difference between LEMS and rotating - machine – classification of LEMSDC linear motors Edge Effect, MMF wave and its velocity, air gap flux density.

#### **Total Hours: 42 Hours**

#### **EE3025 ELECTRIC POWER UTILIZATION**

#### Prerequisite: EE3004 Power Systems I

Electric Traction: Features of an ideal traction system-systems of electric traction- mechanism of train movement Speed control Schemes-Electric braking, Electric heating: classification- heating element-losses in oven and efficiency- resistance furnace- radiant heating- induction heating- high frequency eddy current heating- -Electric welding:- methods and equipments- Electrolysis and Electroplating applications. Illumination: radiant energyterms and definitions- laws of illumination- polar curves- photometry- MSCP- integrating sphere- luminous efficacy- colorimeter, design of interior and exterior lighting systems- illumination levels for various purposeslight fittings- factory lighting- flood lighting-street lighting-energy conservation in lighting. Air conditioning and refrigeration: Control of temperature - protection of motors. Technology of electric and hybrid electric vehicles.

**Total Hours: 42 Hours** 

#### **EE3026 DYNAMIC ANALYSIS OF ELECTRICAL MACHINES**

#### Pre-requisites: EE2007 Electrical Machines I & EE3003 Electrical Machines II

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Electro dynamical equation and their solution- Condition for conversion of average power- Voltage and torque equation of a primitive 4 winding commutator machine- Three phase to two phase and commutator transformation of three phase induction and synchronous machine, voltage and torque equation, steady state, transient and small signal analysis- Dynamical analysis of interconnected machines.

#### **Total Hours: 42 Hours**

#### **EEU 3027 LINEAR SYSTEM THEORY**

**Pre-requisites:** None

Introduction to the concepts of dynamic systems modelling and analysis design and development-System Dynamics-Modelling of electrical systems- passive networks- d c and a c motors linear models -transfer functions for simple electrical and electromechanical systems. n- convolution -block diagrams and signal flow graphs- Mason's gain formula. Modelling of non-electrical systems-Development of linearised models-Superposition principle- Fourier representation of aperiodic signals- Fourier transform and inverse Fourier transform pairs- Stability of linear systems Routh Hurwitz criterion - limitations.Time domain and Frequency domain analysis. Computer simulation of systems.

**Total Hours: 42 Hours** 

#### **EE 3028 HIGH VOLTAGE ENGINEERING**

**Pre-requisites : None** 

Generation of High AC, DC and impulse voltages, Generation of switching surge voltage and impulse currents, Measurement of high voltages and currents-DC, AC and impulse voltages and currents, High voltage testing of materials and apparatus-preventive and diagnostic tests- Natural causes of over voltages - principles of insulation co-ordination, Different types of insulating materials and reasons for breakdown, Insulating materials used in various equipments.

#### **Total Hours: 42 Hours**

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#### **EE3029 NON-CONVENTIONAL ENERGY SYSTEMS AND APPLICATIONS**

**Pre-requisites : None** 

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Renewable energy systems- Principles- Solar energy- solar collectors-solar water heaters- Applications Solar thermal power generation- Solar Photovoltaics- equivalent circuit -MPPT algorithms- Wind energy- wind turbines- characteristics- Dynamics matching- applications- Storage Devices- Super capacitor-SMES- Battery storage-flywheel storage- compressed air storage- Fuel cells-types and applications; MHD generators-Bioenergy- Ocean Energy- mini, micro and pico hydel power

#### **Total Hours: 42 Hours**

#### **EE 3030 APPLICATIONS OF ANALOG INTEGRATED CIRCUITS**

#### Pre-requisite: EE 2004 Basic Electronic Circuits & EE 2008 Analog Electronic Circuits

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Internal analysis of a typical BJT Opamp and a typical CMOS Opamp –Linear and Non-linear application of Opamp – Operational Transconductance Amplifiers and applications – Active Opamp-RC filters -Log/Antilog Amplifiers and Applications, Analog Multipliers . Log / Antilog , Transconductance Type and TDM Type .Applications of Multipliers - True RMS to DC Converters - Phase-Locked Loops, Monolithic PLLs, PLL Applications- Direct Digital Synthesis of Waveforms. Hardware Design Techniques. Grounding and Shielding, Power Supply Filtering and Noise reduction, Grounding in Mixed Signal Systems, EMI/RFI considerations.

**Total Hours: 42 Hours** 

#### **EE3091 ELECTRICAL MACHINES LAB I**

Pre-requisite: EE2007 Electrical Machines I

12 Ex	periments on	characteristics	of DC	Generators.	DC Motors and	Transformers
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**Total Hours: 42 Hours** 

#### **ME3094 MECHANICAL ENGINEERING LABORATORY**

Pre-requisite: ME2007 Mechanical Engineering

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**DETAILED SYLLABI** 

#### EE 3001 MICROPROCESSORS AND MICROCONTROLLERS

**Pre-Requisites : None** 

#### **Total Hours : 42 Hours**

#### Module 1:

**Basics of computer** – Number systems – Computer languages of different levels – compilers – cross compilers - History of Microprocessors – Computer architecture (Block diagram) – Memory types, Addressing concept.

#### Module 2:

#### Microcontrollers

**Microchip PIC 18F 452 Microcontroller** - Introduction - Architecture – Memory organization - Assembly Language programming – simulation using MPLAB IDE - Programming of I/O ports – Addressing modes - Bank switching – Table processing – Timers and its programming – Interrupt programming.

#### Module 3:

**Intel 8086 processor-** Architecture — addressing modes – Instruction set – assembly Language programming – Interrupts Pin configuration of 8086 – Timing diagrams – Minimum and maximum mode –address decoding.

#### Module 4:

**Interfacing chips** – Programmable peripheral interface (8255) - Programmable timer (8253)- -serial communication interface (8251) –DMA controller (8257) - Programmable Interrupt Controller (8259).

#### **Text/Reference Books**

- Muhammad Ali Mazidi, Rolin D.Mckinlay, Danny Causey. PIC microcontroller and Embedded Systems. 2008 1<sup>st</sup> Edition, Pearson Education.
- 2. Lyla B Das The x86 Microprocessors 1<sup>st</sup> Edition Pearson Education, 2010
- 3. T R Padmanabhan Introduction to Microcontrollers and their applications 1<sup>st</sup> Edition 2007 Narosa Publishing House Pvt Ltd..
- 4. Hall D V, Microprocessors & Interfacing, Second Edition, 1991 McGraw Hill.
- 5. Brey B B , The Intel Microprocessors, Architecture , Implementation & Programming,

2005,7<sup>th</sup> edition, McGraw Hill

- 6. Peter Norton Peter Norton's Intro to Computers, 6<sup>th</sup> Edition, 2006, McGraw Hill.
- 7. Dr Badri Ram Fundamentals of Microprocessors and Microcomputers . 3<sup>rd</sup> Edition, 1989, Dhanpat Rai & Sons.

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#### EE3002 CONTROL SYSTEMS -1

**Pre-requisites : None** 

#### **Total Hours: 42**

#### Module 1:

General scheme of control systems – open loop and closed loop – SISO and MIMO systems- effect of feedback in SISO systems- regulator and tracking systems- feedback control strategies – ON-OFF, P, PI ,Pd and PID control – Modelling of dynamic systems- Transfer function – DC Motor-AC Motor- Thermal and pneumatic systems- Control actuators – power amplifiers – amplidyne-magnetic amplifier- pneumatic and hydraulic actuators- sensors and control valves- tachometer- shaft encoders- synchro and flow sensors..

Transfer function and impulse response (review)- derivation for typical closed loop systems- block diagrams reduction and signal flow graphs – Mason's gain formula.

State space modeling- concept of state – state equations general formulation – matrix-vector formulation for linear systems- state model for typical systems- state space model from differential equations and transfer function – canonical models - non-uniqueness of state models -transfer function from state model

#### Module 2:

Time domain analysis of SISO control systems- standard test inputs- impulse, step, ramp and sinusoidal inputsunder damped and over damped responses – first order systems – time constant – second order systems- damping factor natural frequency –and other transient response specifications- higher order systems – steady state error and error constants – error for polynomial type inputs –

Solution of linear time invariant state equation – zero input (free) and zero state(forced) responses – state transition matrix- definition and properties- complete response – output response – bounded input bounded output – eigen values and nature of responses.

#### Module 3:

Stability of linear systems – BIBO stability – characteristic equation roots and stability – Routh Hurwitz criterion for stability – stability from eigen values of system matrix.

Frequency domain methods – root locus techniques – frequency response plots – Polar plots and Bode plots – stability from open loop gain functions – Nyquist criterion – relative stability – gain margin, phase margin etc from polar plot and Bode plot – stability from Bode plot. Frequency domain specifications – band width- cut of frequency etc - Closed loop frequency domain specifications-peak resonance and resonant frequency- correlation with time domain parameters.

#### Module 4:

Introduction to Sampled data and discrete time systems-Sampling Process- uniform rate sampling - ideal sampler- Definition of Z Transform and Inverse Z Transform-Z-Transform & Inverse Z Transform pairs-Theorems of Z transform-Sample & Hold- Zero order Hold-Finite pulse width sampling-Examples for finding z-Transform and Inverse z-Transforms. Pulse transfer functions - State model for discrete time systems- time response from z transform and state models.

#### **Text/Reference Books:**

- 1. Modern Control Engineering, Katsuhiko Ogata, Pearson Prentice Hall, 2006
- 2. Control Systems, M Gopal, Tata McGraw Hill, 3<sup>rd</sup> Edition, 2006
- 3. Modern Control Engineering, K P Mohandas, Revised Edition, Sanguine Pearson, 2010.
- 4. Digital Control Systems, Benjamin C Kuo, Oxford University Press, 1992.

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#### **EE3003 ELECTRICAL MACHINES II**

**Prerequisite:** None

#### **Total Hours: 42 Hours**

#### Module 1: Alternators

Construction - principle of operation - type and selection - armature reaction - voltage regulation - predetermination of voltage regulation - EMF method - synchronous reactance and short circuit ratio - MMF method - Potier method - phasor diagrams - two reaction theory - modified phasor diagram - analysis by two reaction theory - sudden short circuit - current waveforms - transient and sub transient reactance - slip test - DC excitation - static excitation - brush less excitation and self excitation - measurement of losses.

#### **Module 2: Synchronous Machines**

Power angle characteristics of cylindrical rotor and salient pole machines - reactance power - active and reactive power control - load sharing upon parallel operation - effect of armature reactance - automatic synchronizing - effect of change in fuel supply and excitation - alternator connected to infinite bus - governor characteristics - synchronizing power and torque - phasor diagram for two identical generators in parallel - locus of generated voltage for constant real power and variable excitation - automatic voltage regulators - synchronous motor - principle of operation - equivalent circuit - effect of load changes on synchronous motor - mechanical load diagram - armature current as function of power developed and excitation - V curves - inverted V curves - O curves - transition of a machine from generator mode to motor mode - phasor diagram - torque and power relations - minimum excitation for given power - hunting - periodicity of hunting - suppression - different starting methods.

#### **Module 3: Induction Machines**

Three phase induction motors - construction - principle of operation - rotor MMF and production of torque - slip and frequency of rotor current - phasor diagram - equivalent circuit - mechanical power developed - maximum torque - torque slip characteristics - losses and power flow - single phasing - no-load and blocked rotor tests circle diagram - effect of deep bar and double cage rotors - effects of air gap flux harmonics - cogging and crawling - line excited and self excited induction generators - single phase induction motors - double revolving field theory - equivalent circuit - applications of all types of induction motors.

#### Module 4: Starting & Speed Control of Induction Motors

Starting methods of three phase induction motors - direct on line starting - auto transformer starting - star delta starting - rotor resistance starting - starters and contactors - basic methods for speed control of three phase induction motors - voltage control - frequency control - rotor resistance control - pole changing - static frequency conversion and slip power recovery scheme - starting methods of single phase induction motors.

#### **Text/Reference Books:**

- 1. Say M. G, Performance & Design of AC Machines, Pitman, ELBS.3<sup>rd</sup> edition, 1983.
- 2. Langsdorf A.S., Theory of AC Machinery, McGraw Hill., 2<sup>nd</sup> edition, 2002.
- 3. Fitzgerald A.E. & Kingsley: Electrical Machinery, Tata McGraw Hill.,6<sup>th</sup> edition, 2003.
- 4. Chapman S.J, Electric Machinery Fundamentals, McGraw Hill., 2<sup>nd</sup> edition, 1991.
- 5. Toro V.D, Electrical Machines & Power Systems, Prentice Hall, 2<sup>nd</sup> edition, 2003.
- 6. Puchestein, Lloyd & Cenrad, Alternating Current Machines, Asia Publishing House., 1962.
- 7. Nagarath I.J. & Kothari D.P, Electric Machines, Tata McGraw Hill, 3<sup>rd</sup> edition, 2004.
- 8. P.S. Bimbra, Generalized Theory of Electrical Machines, Khanna Publishers, 2001

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#### **EE3004 POWER SYSTEMS – I**

**Pre-requisites : None** 

#### **Total Hours: 42 Hours**

#### Module 1:

Conventional sources of electrical energy - thermal, hydroelectric, diesel and nuclear power plants - renewable energy sources - power plant economics - operating costs - load factor - demand factor - diversity factor - plant factor - tariffs-distributed generation-microgrid-smartgrid.

#### Module 2:

Overhead transmission systems - arrangement of conductors - sag and tension - transmission line supports - choice of transmission voltage - line insulators - failure of insulation - corona - underground cables - different types - capacitance of single core and three core cables - grading of cables.

#### Module 3:

Distribution systems - classification and arrangement of distribution systems - distribution substation layout and arrangement - economic loading of distribution transformers - Kelvin's law - considerations in primary and secondary distribution system design - current distribution and voltage drop calculation-design of feeders and distributors - improvement of existing distribution systems - LT capacitor installation – System and equipment earthing-Energy Conservation Measures- Power quality issues and mitigation techniques-distribution system planning and automation-traction-heating-welding-lighting.

#### Module 4:

Switch gear and protection .Circuit breaker-Types-rating .Selection -Neutral earthing .Lightning and protection - Protective Relays-Functions-Types of Relays-protection schemes- NEC and importance of relevant IS/IEC Specifications

#### **Text/Reference Books:**

- 1. Soni, Gupta, Bhatnagar, "A course in Electric Power", Dhanpat Rai & Sons, NewDelhi, 9 ed., 1996.
- A.T. Starr, "Generation, Transmission & Utilization of Electric Power", Sir Issac Pitman and Sons, 4 ed., 1973
- 3. Turan, Goren, "Electric Power Transmission System Engineering", John Wiley, 1988
- 4. S.L. Uppal, "Electric Power", Khanna Publishers, 1992.
- 5. A.S. Pabla, "Electric Power Distribution System", Tata McGraw Hill, 1992.
- 6. M N Bandyopadhyay, "Electrical Power Systems- Theory and Practice", Prentice Hall of India, 2006.
- 7. Weedy B M, Cory B J, "Electric Power Systems", John Wiley Publication, 4 ed., 1998.
- 8. Sunil S Rao, "Switch Gear Protections", Khanna Publications, Delhi 1999
- 9. T S Madhav Rao, "Power system protection static relays with microprocessor Applications", Tata McGraw hill Publication,1998.
- 10. Badri Ram, D N Vishwakarma, "Power System Protection and Switchgear', Tata Mc Graw Hill, 2005.

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## **EE3021 ELECTRICAL ENGINEERING MATERIALS**

**Pre-requisites:** None

#### **Total Hours: 42 Hours**

#### Module 1:

Conducting materials: Review of metallic conduction on the basis of free electron theory-electrical and thermal conductivity-Wiedemann-Franz law-drawback of classical theory-quantum free electron theory- Fermi-Dirac distribution - variation of conductivity with temperature and composition, Materials for electric resistances-general electric properties: brushes of electrical machines, lamp filaments ,fuses and solder.

Semiconductors: Mechanism of conduction in semiconductors. density of carriers in intrinsic semiconductors - the energy gap - types of semiconductors. Hall Effect - compound semiconductors - basic ideas of amorphous and organic semiconductors

Magnetic materials: Classification of magnetic materials - origin of permanent magnetic dipoles - ferromagnetism - hysterisis curve-magnetostriction - hard and soft magnetic materials- magnetic materials used in electrical machines instruments and relays.

#### Module 2:

Dielectrics: Dielectric polarization under static fields - electronic, ionic and dipolar polarizations - behavior of dielectrics in alternating fields - mechanism of breakdown in gases, liquids and solids- factors influencing dielectric strength- capacitor materials-Ferro and piezo electricity

Insulating materials-complex dielectric constant - dipolar relaxation . dielectric loss insulator materials used - inorganic materials (mica, glass, porcelain, asbestos) - organic materials (paper, rubber, cotton silk fiber, wood, plastics, bakelite) - resins and varnishes - liquid insulators(transformer oil) - gaseous insulators (air, SF6, and hydrogen) – ageing of insulators.

#### Module 3:

Special purpose materials and processes: Thermo couple materials-soldering materials- fuse materials-contact materials-structural materials-fluorescent and phosphorescent materials- galvanizing and impregnation process –

 $Super \ conductors \ - \ effect \ of \ magnetic \ field- \ Meissner \ effect-type \ I \ and \ type \ II \ superconductors \ -London \ equations \ -Josephson \ effect \ -applications \ of \ superconductors$ 

#### Module 4:

Materials for electronic components – resistors –insulated moulded resistors-Cracked carbon resistors-alloy resistors-metallic oxide thin film resistors-High value resistors-wire wound resistors-non linear resistors – varistors –capacitors-mica- dielectric capacitors-glass-dielectric capacitors-plastic-dielectric capacitors etc – inductors –air cored coils –cored coils-ferrite core-relays-

#### **Text/Reference Books:**

- 1. Indulkar C.S.& Thiruvengadam S, An Introduction to ElectricalEngineering Materials, S. Chand Co,1998.
- 2. P.K. Palanisamy ,Solid State Physics, SCITECH Publications,Hyderabad, 2004
- 3. A.J. Dekker,"Electrical Engineering Materials" Prentice Hall of India
- 4. Yu Koritsky, Electrical Engineering Materials., MIR, 1970
- 5. Arumugam M., Materials Science., Anuradha Publishers, 1990
- 6. Kapoor P.L., Electrical Engineering Materials., Khanna Publications,
- 7. Hutchison T.S. & Baird D.C, The Physics of Engineering Solids., John Wiley Publications

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- 8. S.O.Kasap, Principles of Electrical engineering Materials and Devices, Tata Mc Graw Hill.
- 9. R.K. Rajput," Electrical Engg. Materials," Laxmi Publications
- 10. T. K. Basak, "Electrical Engineering Materials" New age International.
- 11. Solymar, "Electrical Properties of Materials" Oxford University Press.
- 12. Ian P. Hones," Material Science for Electrical and Electronic Engineering," Oxford University Press.
- 13. Meinal A.B.& Meinal M.P, Applied Solar Energy -An Introduction., Addison Wesley Publications,1977.
- 14. TTTI Madras, Electrical Engineering materials, Tata Mc Graw Hill, 1999.

#### **EE3022 NETWORK ANALYSIS & SYNTHESIS**

#### Pre-requisite: EE2005 Circuits & Networks

#### **Total Hours : 42 Hours**

#### Module 1: - Network Analysis using Linear Graph Theory

#### Network Topology:

Linear Oriented Graphs - incidence matrix - Kirchoff's Laws in incidence matrix form - nodal analysis (with independent and dependant sources) - Circuit matrix of linear oriented graph - Kirchoff's laws in fundamental circuit matrix form - Loop analysis of networks (with independent and dependant sources) - Planar graphs -Mesh analysis- Duality - Cut set matrix - Fundamental cut set matrix - Relation between circuit, cut set and incidence matrices - Kirchoff's laws in fundamental cut set form - Node pair analysis - Analysis using generalized branch model (node, loop and node pair analysis) - Tellegen's theorem for lumped parameter network in topological form.

#### Module 2: - Network Functions and Elements of Realizability

#### **Review of Network Functions:**

Network functions for one port and two port networks - Poles and Zeros of network functions - Restrictions on pole and zero locations for driving-point functions - Restrictions on pole and zero locations for transfer functions - Concept of stability

#### Elements of Realizability:

Hurwitz polynomials - properties - Brune's positive real functions - Properties of positive real functions -Necessary and sufficient conditions for positive real functions - Sturm's test for positive real functions

#### Module 3: - Synthesis of reactive one - port networks

Elementary synthesis operations:

Removal of pole at infinity - Removal of pole at zero - Removal of conjugate imaginary poles- Synthesis procedure

#### Driving point synthesis:

Frequency response of reactive one ports - Synthesis of reactive one-ports by Foster's and Cauer's methods -Synthesis of LC driving-point functions - Properties of driving point immitances - Pole Zero interpretation -First and Second Foster forms of LC networks - First and Second Cauer forms of LC networks - Synthesis of RC and RL driving-point functions - Properties of RC network functions - First and Second Foster forms of RC networks - First and Second Cauer forms of RC networks - Properties of RL network functions - First and Second Foster forms of RL networks -First and Second Cauer forms of RL networks - RLC one terminal-pair network synthesis - Minimum positive real functions - Brune's method of RLC synthesis - Series Parallel realization - Chop- chop method - The method of Bott and Duffin - Actual realization difficulties

#### Module 4: - Synthesis of reactive two - port networks

Two terminal-pair synthesis – Some properties of  $y_{12}$  and  $z_{12}$  – The coefficient conditions – Transfer immittances with positive coefficients - Constant resistance symmetric lattice - Zeros of transmission - The LC ladder development - Common ground impedance and admittance synthesis - Zero shifting by partial pole removal - Zero producing by complete pole removal - The RC ladder development - Gullimen's transfer admittance synthesis

#### **Text/Reference Books**

- 1. Van Valkenburg M.E: Introduction to Modern Network Synthesis, John Wiley & Sons, 1962.
- K. S. Suresh Kumar, *Electric Circuits and Networks*, 1<sup>st</sup> Ed, Pearson Education, 2009 2.
- Umesh Sinha, Network Analysis & Synthesis, 5th Ed, Satyaprakashan, 2001. 3.
- Van Valkenburg M.E: Network Analysis, Prentice Hall India, 1989 4.
- 5. Dov Hazony, Elements of Network Synthesis, East West Publishers, 1971.
- 6. Franklin F Kuo, Network Analysis and Synthesis, John Wiley, 2001

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### **EE3023 OPTIMIZATION TECHNIQUES AND ALGORITHMS**

**Pre-Requisites : None** 

#### **Total Hours: 42 Hours**

#### Module 1:

Concepts of optimization: Engineering applications-Statement of optimization problem-Classification - type and size of the problem.

Classical Optimization Techniques: Single and multi variable problems-Types of Constraints Semi definite casesaddle point.

Linear programming: Standard form-Geometry of LP problems-Theorem of LP-Relation to convexity - formulation of LP problems - simplex method and algorithm -Matrix form- two phase method.

Duality- dual simplex method- LU Decomposition. Sensitivity analysis. Artificial variables and complementary solutions-QP.

Engineering Applications: Minimum cost flow problem, Network problems-transportation, assignment & allocation, scheduling. Karmarkar method-unbalanced and routing problems.

#### Module 2:

Nonlinear programming: Non linearity concepts-convex and concave functions- non-linear programming - gradient and Hessian.

Unconstrained optimization: First & Second order necessary conditions-Minimization & Maximization-Local & Global convergence-Speed of convergence.

Basic decent methods: Fibonacci & Golden section search - Gradient methods - Newton Method-Lagrange multiplier method - Kuhn-tucker conditions . Quasi-Newton method- separable convex programming - Frank and Wolfe method, Engineering Applications.

#### Module 3:

Nonlinear programming- Constrained optimization: Characteristics of constraints-Direct methods-SLP,SQP-Indirect methods-Transformation techniques-penalty function-Lagrange multiplier methods-checking convergence- Engineering applications

#### Module 4:

Dynamic programming: Multistage decision process- Concept of sub optimization and principle of optimality-Computational procedure- Engineering applications.

Genetic algorithms- Simulated Annealing Methods

Optimization programming, tools and Software: MATLAB- SIMULINK, FSQP, SOLVER, LINDO etc.

#### **Text/Reference Books:**

- 1 David G Luenberger, "Linear and Non Linear Programming", 2<sup>nd</sup> Ed, Addison-Wesley Pub.Co., Massachusetts, 1973
- 2 W.L.Winston, "Operation Research-Applications & Algorithms", Thomson publications, 2003.
- 3 S.S.Rao, "Engineering Optimization", 3<sup>rd</sup> Ed., New Age International (P) Ltd, New Delhi,2004
- 4 W.F.Stoecker, "Design of Thermal Systems", 3<sup>rd</sup> Ed., McGraw Hill, 1989.
- 5 G.B.Dantzig, "Linear Programming and Extensions", Princeton University Press, 1963.
- 6 L.C.W.Dixton, "Non Linear Optimization: theory and algorithms", Birkhauser, Boston, 1980
- 7 Bazarra M.S, Sherali H.D. & Shetty C.M., "Nonlinear Programming Theory and Algorithms", John Wiley, New York, 1979.
- 8 Kalyanmoy Deb, "Optimization for Engineering Design-Algorithms and Examples", Prentice Hall India-1998

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#### **EE3024 SPECIAL MACHINES AND LINEAR MACHINES**

Prerequisite: EE2007 Electrical Machines I

#### **Total Hours: 42 Hours**

#### Module 1: Servo Motors

Servo motors -Requirement of a good servomotor, Types of servomotors: D. C. servomotor: Basic working principle and its classification, Field controlled and Armature controlled DC servomotor, Application: servo-stabilizer and position control system. AC servo motor: construction, operating principle and Application. Symmetrical components applied to two - phase servo motors -equivalent circuit and performance based on symmetrical components - servo motor torque - speed curves.

#### **Module 2: Stepper Motors**

Stepper motors - construction features - method of operation - drive - amplifiers and transistor logic -Drive Circuits - half stepping and the required switching sequence - the reluctance type stepper motor - ratings. Characteristics of Stepper Motor- Stepper motor application.

#### Module 3:

**Reluctance motors** - General types of synchronous motors - Reluctance motors - definitions - construction - polyphase and split phase reluctance motors - capacitor type reluctance motors

**Hysteresis motors** - Construction - polyphase - capacitor type and shaded pole hysteresis motors –Methods of reversing direction of rotation in shaded pole motor. Advantage over reluctance motors, Torque develop and slip

**Universal motors** – Applications - torque characteristics - essential parts of universal motors - EMF due to main filed and cross field - Transformer and rotational emf - circuit model and Phasor Diagram.

#### Module 4: Linear Machines

Linear machines - basic difference between LEMS and rotating - machine – classification of LEMS, linear motors and levitation machines - linear induction motors - linear synchronous motors - DC linear motors - linear levitation machines, Edge Effect, MMF wave and its velocity, air gap flux density

#### **Text/Reference Books**

- 1. Toro.V.D, "Electric machines and power systems", Prentice Hall of India, 1985.
- 2. Veinott, "Fractional horse power electric motors", Mc Graw Hill, 1948
- 3. Nasar.S.A,Boldeal, "Linear Motion Electric machine", John Wiley,1976
- 4. V.U.Bakshi U.A.Bakshi, "Electrical Circuits And Machines", Technical Publication, Pune, 2008.
- 5. V V Athani, "Stepper Motors: Fundamentals Applications and Design", New Age International 2007.
- 6. Fitzgerald, Charles Kingsley, Stephen D. Umans, "Electric machinery", Tata McGraw-Hill 2002.

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#### **EE3025 ELECTRIC POWER UTILIZATION**

#### Prerequisite: EE3004 Power Systems I

#### **Total Hours: 42 Hours**

#### Module 1: Electric Traction

Electric Traction: Features of an ideal traction system-systems of electric traction- mechanism of train movement- speed-time curve, Power and Power Measurement, traction supply system- transmission line to substation- feeding and distributing system on an ac traction- system of current collection-traction motorstractive effort and horse power- Speed control Schemes-Electric braking.

#### Module 2: Electric Heating

Electric heating: classification- heating element-losses in oven and efficiency- resistance furnace- radiant heating- induction heating- high frequency eddy current heating- dielectric heating- arc furnace- heating of buildings-Electric welding:- methods and equipments- Electrolysis and Electroplating applications, Heating of Bare Conductors.

#### **Module 3: Illumination**

Illumination: radiant energy-terms and definitions- laws of illumination- polar curves- photometry- MSCPintegrating sphere- luminous efficacy- electrical lamps- Color values of illuminates and color effects: colorimeter, artificial daylight, design of interior and exterior lighting systems- illumination levels for various purposes- light fittings- factory lighting- flood lighting-street lighting-energy conservation in lighting.

#### **Module4: Air-Conditioning and Refrigeration**

Air conditioning and refrigeration: Control of temperature - protection of motors - simple heat load and motor calculations. Air-conditioning - function of complete air conditioning system - type of compressor motor. Cool storage - estimation of tonnage capacity and motor power. Technology of electric and hybrid electric vehicles.

#### **Text/Reference Books:**

- 1. Taylor E Openshaw, "Utilisation of Electric Energy", Orient Longman, 1986.
- 2. J B Gupta, "Utilization of electric power and electric traction", S K Kataria & Sons, 2002.
- 3. Wadhwa. C.L., "Generation, Distribution and utilization of electrical energy", Wiley Eastern Limited, 1993.
- 4. Soni, Gupta, Bhatnagar, "A course in electric power", Dhanapat Rai & sons, 2001.
- 5. S.L.Uppal, "Electrical Power", Khanna pulishers, 1988.
- 6. Partab H., "Art and Science of Utilisation of Electrical Energy", Dhanpat Rai and Sons, New Delhi. Second edition
- 7. Tripathy S.C., "Electric Energy Utilization And Conservation", Tata McGraw Hill, 1993 .
- 8. Web sites: bee-india.org, eia.doe.gov, www.irfca.org.
- 9. IEEE bronze book-IEEE press
- 10. William Edward Barrows, "Light, Photometry and Illumination", BiblioBazaar, LLC, 2009

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#### **EE3026 DYNAMIC ANALYSIS OF ELECTRICAL MACHINES**

#### Pre-requisites: EE2007 Electrical Machines I & EE3003 Electrical Machines II

#### **Total Hours: 42 Hours**

#### Module 1:

Electro dynamical Equations and their Solution . A Spring and Plunger System- Rotational Motion System . Mutually Coupled Coils . Solution of Electrodynamical Equations by Euler's method and Runge-Kutta method . Linearisation of the Dynamic Equations and Small Signal Stability . Differential Equations of a smooth air-gap two winding machine . Conditions for Conversion of Average Power in such a Machine . A two phase machine with current excitation - Interpretation of the Average Power Conversion Conditions in terms of air-gap Magnetic Fields. The Primitive 4 Winding Commutaor Machine- The Brush Axis and its Significance . Self and Mutually induced voltages in the stationary and commutator windings . Speed e.m.f induced in Commutator Winding . Rotational Inductance Coefficients . Sign of Speed e.m.f terms in the Voltage Equation . The Complete Voltage Equation of Primitive 4 Winding Commutator Machine . The Torque Equation . Analysis of Simple DC Machines using the Primitive Machine Equations.

#### Module 2:

The Three Phase Induction Motor . Equivalent Two Phase Machine by m.m.f equivalence . equivalent two phase machine currents from three phase machine currents . Power Invariant Phase Transformation . Voltage Transformation . Voltage and Torque Equations of the Equivalent Two Phase Machine . Commutator Transformation and its interpretation . Transformed Equations . Different Reference Frames for Induction Motor Analysis . Nonlinearities in Machine Equations . Equations under Steady State - Solution of Large Signal Transients in an Induction Machine . Linearised Equations of Induction Machine . Small Signal Stability . Eigen Values . Transfer Function Formulation.

#### Module 3:

The Three Phase Salient Pole Synchronous Machine . Three Phase to Two Phase Transformation . Voltage and Torque Equations in stator, rotor and air-gap field reference frames . Commutator Transformation and Transformed Equations . Parks Transformation . Suitability of Reference Frame Vs kind of Analysis to be Carried out . Steady State Analysis . Large Signal Transient Analysis . Linearisation and Eigen Value Analysis . General Equations for Small Oscillations . Small Oscillation Equations in State Variable form . Damping and Synchronizing Torques in Small Oscillation Stability Analysis . Application of Small Oscillation Models in Power System Dynamics.

#### Module 4:

Dynamical Analysis of Interconnected Machines . Machine Interconnection Matrices . Transformation of Voltage and Torque Equations using Interconnection Matrix . Large Signal Transient Analysis using Transformed Equations . Small Signal Model using Transformed Equations . The DC Generator/DC Motor System . The Alternator /Synchronous Motor System . The Ward-Leonard System . Hunting Analysis of Interconnected Machines Selection of proper reference frames for individual machines in an Interconnected System.

#### **Text/Reference Books:**

- Sengupta D P & J.B. Lynn, "Electrical Machine Dynamics", The Macmillan Press Ltd. 1.
- 2. Jones C V, "The Unified Theory of Electrical Machines", Butterworth, London.
- 3. Woodson & Melcher, "Electromechanical Dynamics", John Wiley & Sons.
- 4. P.C. Kraus, "Analysis of Electrical Machines", McGraw Hill Book Company

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#### **EEU 3027 LINEAR SYSTEM THEORY**

**Pre-requisites:** None

#### **Total Hours: 42 Hours**

#### Module 1:

Introduction to the concepts of dynamic systems modelling and analysis design and development-Definition of system –System Dynamics--Feedback-Classification of systems- static, dynamic, linear, non-linear, time varying, time invariant, distributed, lumped, continuous time, discrete time, discrete event, systems etc.-Modelling of electrical systems- passive networks- d c and a c motors linear models –Concept of transfer function – transfer functions for simple electrical and electromechanical systems. Impulse response and transfer function- convolution –block diagrams and signal flow graphs- Mason's gain formula

#### Module 2:

Modelling of non-electrical systems- Examples of simple pneumatic, hydraulic and thermal and liquid level systems-control valves - Translational and rotational systems- D'Alembert's principle-Modelling of electromechanical systems, force-voltage and force-current analogy- Comparison of RLC Circuits and Mass-Spring-Damper system- Development of linearised models- Superposition principle-Linearized model for Inverted Pendulum. Introduction to Time delay systems.

#### Module 3:

Fourier representation of aperiodic signals- Fourier transform and inverse Fourier transform pairs-Properties of Fourier transforms. Continuous amplitude and phase spectra-Relation between Laplace transforms and Fourier transforms. Concepts of attenuation, amplification and filtering of signals.

Stability of linear systems – open loop and closed loop stability – bounded input bounded output stability -Routh Hurwitz criterion – limitations

#### Module 4:

Time domain and Frequency domain analysis of single input-single output linear time invariant systems-Determination of Impulse response-Analysis of response to other standard inputs- step, ramp ,acceleration and sinusoidal inputs- Time domain performance measures for first order and second order systems- under-damped and over-damped systems- Significance of damping factor. Definition of order and type of dynamical systemssteady state and dynamic error-Determination of error constants from transfer functions- Analysis of response of higher order systems- Effect of poles and zeros. Frequency response – Bode plots – performance criteria in frequency domain – band width – cut off frequency – gain margin –phase margin. Computer simulation of systems.

#### **Text/Reference Books:**

- 1. David K Cheng: Analysis of Linear Systems, Narosa Publishers, 1998.
- 2. Gene F Franklin, J David Powell, Abbas Emami Naeini, *Feedback Control of Dynamic Systems*, 4<sup>th</sup> Ed, Pearson Education Asia, 2002
- 3. M. Gopal Control Systems Engineering, Tata McGrah Hill, 2008.
- 4. John J D'Azzo, Constantine H Houpis, Stuart N. Sheldon, *Linear Control System Analysis & Design with MATLAB*, 5<sup>th</sup> Ed, Marcel Dekker, 2003
- 5. Burton T.D., Introduction to Dynamic Systems, McGrawHill, 1994
- 6. John Dorsey, Continuous & Discrete Control Systems, McGrawHill, 2002.
- 7. Wayne H Chen, The Analysis of Linear Systems, McGrawHill, 1963.
- 8. Benjamin Kuo, Automatic Control Systems, 7th Ed, Prentice Hall India, 1995.
- 9. Norman S. Nise, Control Systems Engineering, 4th Ed., John Wiley, 2004
- 10. Chi-Tong Chen, Linear System Theory and Design, Oxford University Press, 1999

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#### **EE 3028 HIGH VOLTAGE ENGINEERING**

**Pre-requisites : None** 

#### **Total Hours: 42 Hours**

#### Module 1:

Generation of High voltages and currents: AC voltages: cascade transformers-series resonance circuits. DC voltages: voltage doubler-cascade circuits-electrostatic machines Impulse voltages: single stage and multistage circuits-wave shaping-tripping and control of impulse generators Generation of switching surge voltage and impulse currents

#### Module 2:

Measurement of high voltages and currents-DC,AC and impulse voltages and currents-DSO-electrostatic and peak voltmeters-sphere gaps-factors affecting measurements-potential dividers(capacitive and resistive)-series impedance ammeters-rogowski coils-hall effect generators

#### Module 3:

High voltage testing of materials and apparatus-preventive and diagnostic tests-dielectric loss measurementsschering bridge-inductively coupled ratio arm bridge-partial discharge and radio interference measurementtesting of circuit breakers and surge diverters

#### Module 4:

Introduction to Insulation materials: Different types of insulating materials, Insulating materials used in various equipments. Breakdown in gas and gas mixtures-breakdown in uniform and non uniform fields-Paschens law-Townsends criterion-streamer mechanism-corona discharge-breakdown in electro negative gases- Breakdown in liquid dielectrics-Breakdown in solid dielectrics.

Natural causes of over voltages- lightning phenomena - over voltages due to switching surges - system faults and other abnormal conditions for different voltage levels- principles of insulation co-ordination

#### **Text/Reference Books:**

- 1. Kuffel and Zaengal, "High Voltage Engineering Fundamentals", Newness, 2 ed.2002
- 2. M. S. Naidu, V. Kamaraju, "High Voltage Engineering", McGraw-Hill, 3 ed., 1995.
- 3. M. Khalifa, "High Voltage Engineering: Theory and Practice", Dekker, 1990.
- 4. H. M. Ryan, "High Voltage Engineering and Testing", IEE 2001.
- 5. Kuffel and Abdullah.M, "High Voltage Engineering", Pergamon press, 1978
- 6. Wadhwa C L, "High Voltage Engineering", New Age International, NewDelhi,1994
- 7. Relevant IS standards and IEC standards
- 8. Haddad A, Warne DF, "Advances in High Voltage Engineering", IEE publication, 2004
- 9. Standard techniques for high voltage testing, IEEE Publication 1978.

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### EE3029 NON-CONVENTIONAL ENERGY SYSTEMS AND APPLICATIONS

**Pre-requisites : None** 

#### **Total Hours: 42 Hours**

#### Module 1:

Introduction to renewable energy various aspects of energy conversion-Principle of renewable energy systemsenvironment and social implications

Solar energy: Solar radiation components- measurements-estimation-solar collectors-solar water heaters-Calculation-Types-analysis-economics-Applications Solar thermal power generation

Solar Photovoltaics- energy conversion principle-classifications-equivalent circuit-characteristics-Cell efficiency- Limitations-PV modules-MPPT algorithms

#### Module 2:

Wind energy: Basics of wind-wind turbines-power and energy from wind turbine-characteristics- - types of electric generators for wind power generation. Dynamics matching- performance of wind generators applications- economics of wind power

#### Module 3:

Storage Devices: Super capacitor-SMES- Battery storage-flywheel storage- compressed air storage- Fuel cells-types and applications; MHD generators - backup -System design-industrial and domestic applications.

#### Module 4:

Bioenergy: Bio fuels-classification-biomass conversion technologies-applications; Ocean Energy: Tidal energy-wave energy-ocean thermal energy conversion systems-applications; - mini, micro and pico hydel power

#### **Text/Reference Books:**

- Godfrey Boyle, "Renewable Energy: Power for a sustainable future", Oxford University press, Second 1. edition.
- Rai G D, "Solar Energy Utilization", Khanna Publishers, 1997. 2.
- B H Khan, "Non-Conventional Energy Resources", The McGraw-Hill Companies, Second Edition. 3.
- Sukhatme, S.P, "Solar Energy -Principles of Thermal Collection and Storage", Tata 4.
- McGraw-Hill, 2 ed., 1997. 5.
- 6. Sammes, Nige, "Fuel Cell Technologies-State and Perspectives", Springer publication, 2005
- 7. Kreith, F., and Kreider, J.F., "Principles of Solar Engineering", Mc-Graw-Hill Book Co, 1978.
- S.L.Soo, "Direct Energy Conversion", Prentice Hall Publication, 1968 8.
- 9. James Larminie, Andrew Dicks, "Fuel Cell Systems", Wiley & Sons Ltd, 2ed, 2003.
- 10. E.J. Womack, "MHD power generation engineering aspects", Chapman, Hall Publication, 1969.

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## **EE 3030 APPLICATIONS OF ANALOG INTEGRATED CIRCUITS**

### Pre-requisite: EE 2004 Basic Electronic Circuits & EE 2008 Analog Electronic Circuits

#### **Total Hours: 42 Hours**

#### Module 1:

Various Stages of an Operational Amplifier, Active Load, Current Mirror -

Simplified Schematic Circuit of a typical BJT Opamp, Bias and Small Signal Analysis of a typical BJT Opamp, Bias and Small Signal Analysis of a typical two-stage CMOS Opamp, Bias and Small Signal Analysis of a typical folded cascode CMOS Opamp

Ideal and practical characteristics of Opamps, Compensating an Opamp, Offset model of opamp and offset analysis of simple application circuits, special design opamps, auto-zero amplifiers, single supply opamps and applications. Noise Dynamics and Properties. Sources of Noise and Low-Noise Op Amps

#### Module 2:

**Applications :** Amplifiers for Signal Conditioning, Schmitt Triggers, analog switches, comparator ICs, precision rectifiers, precision clipping circuits, Sine, Triangular, Sawtooth, and Monolithic Wave Generators, Multivibrators, V-F and F-V Converters, VCO Circuits, Timers.Voltage References and Regulators. Switching, linear, and monolithic switching regulators. Switching Regulator Control ICs , Battery Charging Control ICs.Operational Transconductance Amplifiers . Applications

#### Module 3:

Active Filters: Categories of Filters, LP,HP,BP,BE and All Pass Filters, Second Order s-domain equations in each case and their pole-zero plots. The Filter approximation problem - Butterworth Approximation, Chebyshev and Inverse Chebyshev Approximations, frequency transformations. Biquad Topologies, Analysis and Design of Single OPAMP Biquads with finite gain . Analysis and design of LP,HP and BP Filter with second order response KHN (Universal Active Filter) Filter, Tom-Thomas Biquad, Analysis and Design for various categories of filters.- OTA .C Tunable Filters.

SC Filters, SC Resistor, First and second Order SC Filters, Structure for LP, HP, BP and BE SC Filters

#### Module 4:

**Applications and Design Techniques:** Log/Antilog Amplifiers and Applications, Analog Multipliers . Log / Antilog , Transconductance Type and TDM Type .Applications of Multipliers - True RMS to DC Converters -

Phase-Locked Loops, Monolithic PLLs, PLL Applications- Direct Digital Synthesis of Waveforms. Hardware Design Techniques. Grounding and Shielding, Power Supply Filtering and Noise reduction, Grounding in Mixed Signal Systems, EMI/RFI considerations.

#### **Text/Reference Books:**

- 1. A.S Sedra and K.C Smith, Microelectronic Circuits., Holt Saunders International Edition-3,1989
- 2. D.H. Sheingold, .Nonlinear Circuits Handbook., Analog Devices Inc. 1976
- 3. Clayton, .Operational Amplifiers., Butterworth Publications, 1979
- 4. Sergio Franco, Design with Operational Amplifiers and Analog Integrated Circuits., Mc Graw Hill, 1988
- 5. M.E Van Valkenburg, Analog Filter Design., Oxford University Press 2001
- 6. National Semiconductor, Linear Applications Handbook., 1994
- 7. Analog Devices Inc, Practical Design Techniques for Thermal and Power Management., 2004
- 8. Analog Devices Inc, RMS to DC Conversion Application Guide.
- 9. Analog Devices Inc., A Designers. Guide to Instrumentation Amplifiers.
- 10. Analog Devices Inc., Practical Design Techniques for Sensor Signal Conditioning.

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### **EE3091 ELECTRICAL MACHINES LAB I**

#### Pre-requisite: EE2007 Electrical Machines I

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#### **Total Hours: 42 Hours**

#### List of Experiments

- 1. Determination of open circuit characteristic of a dc shunt generator and its analysis.
- 2. Load test on a dc shunt generator, determination of internal/ external characteristics and analysis.
- 3. Break test on dc shunt and series motors, determination of performance characteristics and analysis.
- 4. Swinburne's test on a dc shunts motor and predetermination of efficiency of the machine.
- 5. Hopkinton's test on a pair of dc shunts machines and predetermination of their efficiencies.
- 6. Retardation test on a dc shunt machine and separation of losses.
- 7. No load test on a dc shunt machine and separation of losses.
- 8. OC and SC tests on a single-phase transformer and predetermination of efficiency/ regulation.
- 9. Separation of losses in a single-phase transformer.
- 10. Sumpner's test on a pair of single-phase transformers and predetermination of efficiency/ regulation.
- 11. Scott connection of two single-phase transformers and performance evaluation.
- 12. Polarity test on single phase transformers and three phase connections of the same.

#### **Text/Reference Books:**

- 1. Clayton & Hancock, Performance & Design Of DC Machines, CBS, 3<sup>rd</sup> edition, 2001
- 2. Langsdorf A.S., Principles of DC Machines, McGraw Hill.6<sup>th</sup> edition, 1959.
- 3. Say M. G, Performance & Design of AC Machines, Pitman, ELBS.3<sup>rd</sup> edition, 1983.
- 4. Langsdorf A.S., Theory of AC Machinery, McGraw Hill., 2<sup>nd</sup> edition, 2002.

### **ME3094 MECHANICAL ENGINEERING LABORATORY**

#### Pre-requisite: ME2007 Mechanical Engineering

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#### Number of Hours: 42

#### Fluid mechanics lab:

Flow measurement -- venturi meter -- nozzle meter -- orifice meter -- notches, Friction factor for various types of flows through pipes, Metacentric height for floating bodies.

#### Hydraulic machinery lab:

Characteristics of turbines – Pelton turbine -- Francis turbine, Characteristics of pumps – centrifugal pump -- reciprocating pump -- gear pump.

#### Heat engines lab:

Properties of oils – viscosity -- flash and fire points, Constant speed characteristics of internal combustion engines – spark ignition engines and compression ignition engines, Characteristics air compressors